# Aditya Abishai Pedapati

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## EDUCATION

#### NEW YORK UNIVERSITY

MS IN MECHATRONICS AND ROBOTICS May 2025 | New York, US

#### VASAVI COLLEGE OF ENGINEER-ING

BE IN MECHANICAL ENGINEERING WITH DISTINCTION May 2023 | Hyderabad, India

## LINKS

Github:// abixxvii LinkedIn:// Abishai A Website:// abixxvii.github.io

## COURSEWORK

#### GRADUATE

Mechatronics Mathematics for Robotics Foundations of Robotics Advanced Mechatronics Robotic Gait and Manipulation Entrepreneurship (Notable Achievements)

Recipient of merit based scholarship

## TECHNICAL SKILLS

#### PROGRAMMING LANGUAGES

C++ • C • Python • MATLAB • Shell scripting

**ROBOTICS AND FRAMEWORKS** ROS (Robot Operating System) • Gazebo • CoppeliaSim • MuJoCo

#### SIMULATION AND MODELING

SolidWorks • Siemens NX • Fusion 360 • CATIA • Ansys Fluent • Unity3D

#### MACHINE LEARNING

PyTorch • OpenCV • JAX • OpenAl Gym VERSION CONTROL Git

#### MICROCONTROLLERS

Arduino • Espressif ESP32 • Raspberry Pi OPERATING SYSTEMS

## Linux • Mac OS • Windows

**OTHER TOOLS** LATEX • Microsoft Office Suite • Adobe Creative Suite

#### MANUFACTURING

CNC Machining • Metalworking • Rapid Prototyping • Welding • Laser Cutting

### EXPERIENCE

#### COOPERSURGICAL, INC | R&D AND NEW PRODUCT DEVELOPMENT INTERN

May 2024 - August 2024 | Trumbull, CT

- Juggled numerous projects delivering innovative solutions and wearing many hats, while leading a cross-functional team.
- Developed a fully-functional Automated ICSI Micromanipulator with submicron precision, minimal backlash, and manual override capability, to be showcased at an upcoming Healthcare Summit.
- Gave a facelift to the fan and temperature modules for the Advanced Micromanipulator, optimizing performance, ease of service, and functionality, while minimizing manufacturing cost.

#### KIA INDIA PVT LTD | PROJECT INTERN

Feb 2023 – May 2023 | Ananthapur, India

- Played a key role in KIA Carens redesign, emphasizing intricate mechanical assemblies with GD&T application and optimizing the BIW (Body in White) and the weatherstrip.
- Collaborated with industry-leading engineers, achieving a defect per unit (DPU) reduction to less than one.
- Analyzed vehicle defects, implemented Root Cause Analysis (RCA), and drafted effective defect reduction strategies.

#### RE SUSTAINABILITY | ENGINEERING INTERN

Jul 2022 – Aug 2022 | Hyderabad, India

- Spearheaded initiatives at the largest waste-to-energy plant in South India, overseeing the production of 28 MW of RDF from 1,200 tons of daily waste.
- Innovatively implemented drone technology to efficiently spray 75 liters of liquid odorite, effectively mitigating unpleasant odors.

#### IIT MADRAS RESEARCH PARK | PROJECT INTERN

April 2022 – July 2022 | Chennai, India

• Engineered a robot mecanum wheels, a 6 DOF robot configuration, and enhanced payload capacity.

## PROJECTS

## **STAIR TRAVERSAL AND EXPLORATION PLATFORM** Jan 2024 |NY, US

Currently collaborating with a team of hard-headed engineers to build a 10 DOF Biped robot(Mark-V).

#### MAZE SOLVING DEVICE May 2024 | NY, US

Engineered a maze-solving device using Raspberry Pi 4B and Arduino Uno, leveraging OpenCV for image processing and breadth-first search algorithms for navigation, with servo-controlled movement for precise ball guidance.

#### AUTOMATIC PACKAGE SEPERATOR Feb 2024 | NY, US

Developed an Automatic Package Separator system using Arduino technology, incorporating a 1D/2D barcode scanner, servo and DC motors, ultrasonic sensor, and LCD display to enhance address-based package segregation efficiency.

#### SONARDUINO Oct 2023 - Nov 2023 | NY, US

Developed a **360 degree radar system** for object detection. Enhanced the capabilities of locomotive robots by providing SonarDuino which helps in object detection.